



INSTALLATION MANUAL

REMOTUS T-Rx Std. T-Rx Std. 500, T-Rx Std. Era 4/6/8B/8B ND, T-Rx Std. 12B/12BD

(RXO, AQ80, TX52/55)





951570-000 EN -B01

Revision history

| Version | Date | Reason |
|---------|------------|--|
| A0 | 2014-12-16 | 1 st released version |
| A1 | 2015-03-30 | Chapters have been moved for better flow and clarifying in the program selection |
| A2 | 2015-08-28 | Program Option 4 added |
| A3 | 2015-11-30 | Program Option 5 added |
| B0 | 2017-01-25 | T-Rx Std. Era 4B, 6B & 8B ND added, external power supply removed |
| B01 | 2017-02-08 | Program option 2 |

Reference

RXO manager, manual 951538-000.

Display control mapping RXO Std. manual 951571-000.

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1 Introduction

Remotus is Åkerströms product family for radio remote control of safety critical industrial and mobile applications. Remotus T-Rx Std. is Åkerströms' standardized mobile remote control product line.

The manual must be used when installing Åkerströms Remotus system to ensure a secure and safe operation. This manual only covers the installation of the Remotus radio remote control system. Remotus does not include a complete system for remote control: it has only a set of outputs that is controlled by the operator with the transmitter switches and joysticks. How the outputs are used to control the object (for example, a machine's movements and brakes) depend on the specific installation and is outside the scope of the Remotus system.

It is the responsibility of the Systems Integrator or Machine builder to safely incorporate the Remotus radio remote control into the complete system or machine. The System Integration has to be made by qualified personnel applying the appropriate standards for the system or machine including making the necessary safety investigations and risk analysis.

It should be noted that the information obtained from the controlled object is not processed by the Remotus receiver, but is used for informational purposes.

For the reasons stated above, the safety of Remotus covers mainly the status of the relay outputs, regardless of the object that is controlled by the relays.

The interface between Remotus and the controlled object should be a special interface that is not included in Remotus system and therefore is not included in this installation manual.

The approvals for Remotus refer only to the Remotus system not the complete system.

The complete radio control system must be tested and approved in accordance with applicable standards. It is not part of Åkerströms Björbos responsibility.

2 Scope

The Remotus T-Rx Std. system described in this manual consists of one receiver and one transmitter.

| | Туре | Model | |
|--------------------|------|---------------------|--|
| Receiver RXO | | T-Rx Std. 500 | |
| | | T-Rx Std. Era 4B | |
| | AQ80 | T-Rx Std. Era 6B | |
| Button transmittor | | T-Rx Std. Era 8B | |
| Dullon transmitter | | T-Rx Std. Era 8B ND | |
| | TX52 | T-Rx Std. 12B | |
| | TX55 | T-Rx Std. 12BD | |



3 Use of warnings and notes in this manual

Read all safety instructions throughout this manual and on safety signs attached to this equipment.

Failure to follow all safety instructions could result in death or serious injury.

The safety alert symbol is used to alert about potential personal injury hazards. To avoid hazards, obey all safety messages that follow this symbol. Inform all personnel that are working with the product. The following safety alert symbols and signal words are used in this manual to inform the user of hazards.



Indicates a potentially risk of high voltage which, if not avoided, could result in death or serious injury or property damage.



Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury or property damage.



Indicates a condition which, if not avoided, could result in damage to or poor functionality of the product.

4 Warnings regarding installation and maintenance work

This manual must be read and understood before installing and starting the radio remote control system to ensure safe and secure operation.

The installation and/or maintenance work must be carried out by a qualified and educated person in accordance with country installation rules and regulations. Only a correct installation can ensure the necessary level of safety during use.



Before any work on the receiver disconnect the power supply.



Disconnect voltage when working with installation wiring. Voltage may be supplied from different power sources.



As the antenna installation may require work to be carried out on the vehicle/machine roof care should be taken to protect personnel from falling.



Read the User Manual before attempting to use the transmitter.

If testing of the installation also includes moving, make sure no personnel or equipment is in the area of moving objects.



Disconnect voltage when connecting/disconnecting connectors. Voltage may be supplied from different power sources.



At high ambient temperatures, the receiver units' surface gets hot. Do not touch the surface. In these situations the receiver shall be installed out of reach.



5 Specifications

| General: | | | | | |
|---|--|---------------------------------------|--|--|--|
| Operating frequency: | 433-434 MHz | | | | |
| Power output: | < 10 mW | | | | |
| Baud rate: | 9600 b/s | | | | |
| Transmission principle: | GFSK, TDMA | | | | |
| Channel Separation: | 25 kHz | | | | |
| Functional sensitivity: | ≤-107 dBm BER 10 ⁻³ | | | | |
| The radio full-fills: | R&TTE Directive 99/5EC | | | | |
| Reaction time on STOP function: | Maximum 550 ms | | | | |
| Safety category for the Stop function | ISO 13849-1 Category 3 PL d | | | | |
| Receiver T-Rx Std. 500: | 5 T T T T T T T T T T T T T T T T T T T | | | | |
| Туре: | RXO | | | | |
| Dimensions: | 240x177x67.5 mm_connectors | sexcluded | | | |
| Weight: | 1.6 kg | | | | |
| Power supply: | 12 V DC nominal (6-16 V DC) | max 0.35 A @12 V DC, outputs excluded | | | |
| rowei suppiy. | 24 V DC nominal (6-16 V DC) max 0,35 A @12 V DC, outputs excluded 24 V DC nominal (10-21 V DC) max 0,175 A @12 V DC, outputs excluded | | | | |
| Operating temperature: | -25 °C - +70 °C | | | | |
| Storage temperature: | -40 °C - +85 °C | | | | |
| Degree of protection: | IP67 | | | | |
| Transmitter T-Rx Std. Era | 4/6/8B: | 8B ND: | | | |
| Туре: | AQ80 | | | | |
| Dimensions: | 181 x 65 x 43 mm | | | | |
| Weight: | 265 g | 255 g (including battery) | | | |
| Degree of protection: | IP67 | | | | |
| Operating Temperature for battery: | -20 °C – +55 °C | | | | |
| Storage Temperature for battery: | -20 °C – +35 °C | - +35 °C | | | |
| Charging Temperature for battery: | +10 °C – +45 °C NOTE! For charging see charg | ng see charger documentation | | | |
| Display: | Graphic LCD, 128x64 pixels | No display | | | |
| Transmitter T-Rx Std. 12B/BD: | | | | | |
| Туре: | TX52/55 | | | | |
| Dimensions: | 243 x 77 x 41 (49 mm incl. safe | ety stop) | | | |
| Weight: | 450 g | | | | |
| Degree of protection: | IP67 | | | | |
| Operating temperature: | -25 °C – +55 °C | | | | |
| Storage temperature: | -40 °C – +85 °C | | | | |
| Battery type: | Li-Ion 3.7V | | | | |
| Operating Temperature for battery: | -20 °C – +55 °C | | | | |
| Storage temperature for battery: | -20 °C – +35 °C | | | | |
| Charging temperature for battery: +10 °C - +45 °C (NOTE! For charging see charger documentation) | | | | | |
| Display (TX55): | Graphic 102*64 pixels | | | | |
| | | | | | |

Table 1. Technical specifications

5.1 Design

The RXO receiver consists of a MAIN board and a radio module. The radio module is located on top of the MAIN board.

The MAIN board holds all logic components, power supply and the connectors.

The enclosure is made of metal.

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5.2 Functional description

The Remotus T-Rx Std. Era system uses a dual channel architecture in the receiver to achieve high degree of safety. For additional safety the receiver RXO is equipped with two safety outputs intended for safety stop.

The dual channel architecture and extensive use of safety outputs in the receiver will significantly increase the safety of the crane system providing that the installation is carried out correctly. To achieve category 3 Pl d for the STOP function according to ISO 13849-1:2006 both safety stop outputs from the receiver shall be connected to two independent stop inputs on the machine (two safety stop channels).



Figure 1. Receiver functional safety description



6 Installation

The installation shall be carried out by qualified personal. Ensure compliance to national and vehicle/ machine depending installation regulations.

The permanent installation of the receiver must include fuses to protect the equipment and wiring from over current and short circuit. In detail the power supply of the receiver and all relay contacts must be fused. Over current protection for the receiver power supply and interface circuit is not provided with this enclosure. Over current protection must be provided as part of the installation.

6.1 Installation preparation

The T-Rx 500 receiver can be operated within a wide ambient temperature range according to the technical specifications below. Due to the additional self-heating, proper derating or cooling is needed.

See chapter "8 Derating".

Select a proper space on the vehicle/machine for the receiver.

- The receiver shall be installed on a flat surface
- · The receiver shall be protected against weather conditions and excessive mechanical damage
- The receiver must be fixed with four screws M5 x L
- Do not install the receiver close to heat generating equipment. As the internal heating of the device electronics is dissipated via the housing, sufficient cooling must be ensured in case of "sandwich mounting"
- Be sure to connect the earth from loads close to the RXO receiver earth to avoid risk of EMC interference
- Do not install the receiver close to equipment likely to produce radio interference disturbance
- Do not install on a structure that is prone to vibration

Make sure that it is possible to install the necessary cabling between the receiver and

- the antenna. Maximum cable length 10 m
- the vehicle/machine control system

The antennas shall be installed on the vehicle/machine on a conductive surface. See chapter "6.5 Antenna installation".

Do not install the antennas close to equipment likely to produce radio interference disturbance

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6.2 Mechanical installation

Note! Make sure to install any optional accessories inside and/or on the receiver enclosure before mounting the receiver on the machine. Refer to each accessory kit for assembly instructions.

The receiver shall be installed on a flat surface or similar construction. Make sure that the structure may support the load of the receiver.

If possible the cable entry of the interface connector should be mounted pointing downwards. Mount the receiver using the mounting slots on each receiver end block as shown in Figure 2 below.

Fasten the receiver with four M5 screws. Fasten the screws with a torque of 2 Nm.



Figure 2. Receiver mounting dimension



6.2.1 Connecting earth to receiver housing

To ensure the receiver against electrical interference the housing shall be connected to ground. If a proper connection is not achieved by the fastening screws an additional earth cable shall be connected to one of the fastening screws of the receiver. Recommended wire size 2.5 mm².

For vehicles, ground refers to vehicle body.

Do not install the receiver on a vehicle/machine with positive grounding.

If the receiver is installed on an industrial truck the receiver must be mounted isolated from the frame. In the antenna cabling a DC block must be used.

Åkerströms can provide one suitable DC block 944498-000.

The insulation resistance between the receiver and the frame shall be at least 1000 Ω multiplied by the nominal voltage of the truck system according to EN 1175-1 + A1, Safety of industrial trucks - Electrical requirements - Part 1: General requirements for battery powered trucks.

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6.3 Connections and switches on the MAIN board

Figure 5. Connections, switches, interface terminals and LED on the MAIN board

6.4 Cable installation



Do not mix SELV and NON SELV signals in the same cable.

Af

After the installation of the equipment, the installed cables must be bound together in pairs (e.g. by using a cable tie) very close to the terminal blocks (see Figure 6). This is important if a cable become loose. The cable should not be able to end up in an unsuitable location of the receiver. Fasten with a torque of 0.4-0.5 Nm.



Figure 6. Installation of cables



6.4.1 Connecting power supply

The power supply is nominal 12/24 V DC, range 6-32 V DC. The input power supply wiring must be sufficiently fused, and if necessary it must be possible to disconnect manually from the DC mains supply.

| Description | Terminal name | Fuse |
|--|---------------|------------|
| Supply voltage receiver/analogue interface | VDD | max. 10 AT |
| Supply voltage output RCSS1 | VDD 1 | max. 10 AT |
| Supply voltage output RCSS2 | VDD 2 | max. 10 AT |
| Supply voltage output Digital 0-3 | VDD 3 | max. 10 AT |
| Supply voltage output Digital 4-7 | VDD 4 | max. 10 AT |
| Supply voltage output Digital 8-11 | VDD 5 | max. 10 AT |
| Supply voltage output Digital 12-15 | VDD 6 | max. 10 AT |
| Supply voltage output Digital 16-19 | VDD 7 | max. 10 AT |
| Supply voltage output Digital 20-23 | VDD 8 | max. 10 AT |
| | | |
| Ground | GND | |

Both RCSS supply lines must be connected for correct functionality of the receiver.

6.4.1.1 Receiver supply

The maximum current consumption is 0.35 A at 12 V DC and 0.175 A at 24 V DC.

The fuse for the input power supply shall be max 10AT, and of slow blow characteristic and high breaking capacity.

If a switch is used for selecting Remote/Manual control the receiver and analogue interface supply (VDD) shall not be connected to the switch together with the supply for other outputs (VDD 1 - VDD 8).

6.4.1.2 RCSS Interface supply

The receiver has two safety outputs, RCSS1 and RCSS2. They shall be connected to the machine safety circuit in such a way that either one of them can stop the machine independently.

The current consumption on each RCSS feeding point is depending on the controlled devices connected to the output, but shall not exceed 3 A. The fuse for each RCSS feeding point shall be max10 AT, and of slow blow characteristic and high breaking capacity.

6.4.1.3 Digital Interface supply

Each feeding point supports four outputs. The current consumption on each feeding point is depending on the controlled devices connected to the outputs, but shall not exceed 3A/output or in all 4 A within the group. The fuse for each feeding point shall be max 10AT, and of slow blow characteristic and high breaking capacity.

6.4.2 Serial interface cabling

For the RS422/485 interface screened cables shall be used. The screen shall be connected to ground.

6.4.2.1 Serial port setup

To configure the serial port on RXO Std. use the RXO manager and please read section 6.4.3.1.3 to see the difference between connections of RS422 and RS485.

In RXO manager there are settings for baudrate, format and a choice between RS422 and RS485 interface. For information about how to control the display please read Display control mapping RXO Std. manual.



6.4.3 Connecting output interface to control equipment

The interface of the receiver consists of:

- 2 RCSS (Remote Control Safety Stop) outputs
- 24 Digital outputs
- 1 RS422 or RS485 interface

6.4.3.1 Connector pin assignment

6.4.3.1.1 RCSS outputs

| Supply line terminal | Function output terminal | | |
|----------------------|--------------------------|--|--|
| VDD 1 | RCSS 1 | | |
| | | | |
| VDD 2 | RCSS 2 | | |

6.4.3.1.2 Digital outputs

| Supply line terminal | Function output terminal |
|----------------------|--------------------------|
| VDD 3 | OUT 0-3 |
| | |
| VDD 4 | OUT 4-7 |
| | |
| VDD 5 | OUT 8-11 |
| | |
| VDD 6 | OUT 12-15 |
| | |
| VDD 7 | OUT 16-19 |
| | |
| VDD 8 | OUT 20-23 |

6.4.3.1.3 RS422/485 interface

| RS422 | RS485 | | |
|--------------------------|--------------------------|--|--|
| Function output terminal | Function output terminal | | |
| Rx+ | | | |
| Rx- | B mp Tr | | |
| Tx+ | | | |
| Tx- | Z – S | | |
| GND | GND | | |

6.4.4 Functional diagram

The receiver functional diagram shows how to connect the equipment, in this manual the functional diagram is written as different program options, see chapter 7.



6.4.5 Principle connection of the Main contactors

The radio remote control system is, for the safety stop function, designed for category 3 Pl d according to ISO 13849-1:2006. To achieve this safety level for the object (crane) both safety stop outputs MC1 and MC2 shall be used as two separate independent outputs (two safety channels). This means that there must be two main contactors on the machine. See the connection example below.



Figure 8. Connection with the two main contactors in parallel, category 3

If category 3 is not desired, the two safety stop outputs MC1 and MC2 shall be used connected in series. See the connection example below. The maximum level of safety for the safety stop function in this case will be category 1.



Figure 9. Connection with the two main contactors in series, category 1

6.5 Antenna installation

The antenna should be installed on a conductive surface with a minimum size of 50×50 cm. The surface shall be electrically connected to vehicle/machine chassis. The maximum allowed cable length between receiver and the antenna is 10 meters.

Do not paint the antennas. Paint might considerable reduce the radio coverage area.

The maximum allowed length of the antenna cables is 10 meters. The connectors on the receiver are of type SMA for radio band 400MHz and 800MHz. Install the antenna cables separated from high voltage or high current cables/devices.



If the antenna is installed outdoors, there is a risk that dangerous voltages may enter the antenna cable. To minimize this risk a DC block shall be used. DC blocks are coaxial components that prevent the flow of low and direct current (DC) frequencies while offering minimum interference to RF signals. Suitable models have capacitors in series with both the inner and outer conductors.

Åkerströms can provide one suitable DC block 944498-000.



7 Program Selection

There are two rotary switches for program selection in the receiver, located behind the service hatch, see "Figure 4. Receiver back side" on page 10.

Note! The switches must be set to the same position Example: Program option 0, set both switches to 0 (0,0)



7.1 Program Selection list

7.1.1 Program Option 0

| Program Option 0 | | | | | | |
|---------------------|-----------|-------------------|----|----|----------|------------|
| Supply line | Connector | Function | | | | Cable part |
| terminal | | 4B | 6B | 8B | 12B/12BD | Cable part |
| | OUT0 | - | - | - | B1 | |
| VDD3 | OUT1 | - | - | - | B2 | |
| Cable part: | OUT2 | - | - | - | B3 | |
| | OUT3 | - | - | - | B4 | |
| | OUT4 | B1 | B1 | B1 | B5 | |
| VDD4 | OUT5 | B2 | B2 | B2 | B6 | |
| Cable part: | OUT6 | - | B3 | B3 | B7 | |
| | OUT7 | - | B4 | B4 | B8 | |
| | OUT8 | - | - | B5 | B9 | |
| VDD5 | OUT9 | - | - | B6 | B10 | |
| Cable part: | OUT10 | B7 | B7 | B7 | B11 | |
| | OUT11 | B8 | B8 | B8 | B12 | |
| VDD8 Cable part: | OUT23 | Activation output | | | | |
| VDD1 Cable part: | RCSS 1 | RCSS 1 | | | | |
| VDD2 Cable part: | RCSS 2 | RCSS 2 | | | | |
| Cable part: | + 24VDC | + 24 V DC | | | | |
| Cable part: | 0VDC | 0 V DC | | | | |



7.1.2 Program Option 1 - Shift function

Note that remaining function never can be shifted in Program 1. (For AQ80 see 9.3.4 and for TX52/55 9.5.4)

| Program Option 1 - Shift function | | | | | | | |
|-----------------------------------|-----------|---------------|------------|------------|-------------|------------|--|
| Supply line | Connector | | Cable part | | | | |
| terminal | Connector | 4B | 6B | 8B | 12B/12BD | Cable part | |
| | OUT0 | - | - | - | B1 | | |
| VDD3 | OUT1 | - | - | - | B2 | | |
| Cable part: | OUT2 | - | - | - | B3 | | |
| | OUT3 | - | - | - | B4 | | |
| | OUT4 | B1 | B1 | B1 | B5 | | |
| VDD4 | OUT5 | B2 | B2 | B2 | B6 | | |
| Cable part: | OUT6 | - | B3 | B3 | B7 | | |
| | OUT7 | - | B4 | B4 | B8 | | |
| | OUT8 | - | - | B5 | B9 | | |
| Cable next | OUT9 | - | - | B6 | B10 | | |
| Cable part: | OUT10 | B7 | B7 | B7 | B11 | | |
| | | SHIFT (B8) | SHIFT (B8) | SHIFT (B8) | SHIFT (B12) | | |
| | OUT12 | - | - | - | B1 + SHIFT | | |
| VDD6 | OUT13 | - | - | - | B2 + SHIFT | | |
| Cable part: | OUT14 | - | - | - | B3 + SHIFT | | |
| | OUT15 | - | - | - | B4 + SHIFT | | |
| | OUT16 | B1 + SHIFT | B1 + SHIFT | B1 + SHIFT | B5 + SHIFT | | |
| VDD7 | OUT17 | B2 + SHIFT | B2 + SHIFT | B2 + SHIFT | B6 + SHIFT | | |
| Cable part: | OUT18 | - | B3 + SHIFT | B3 + SHIFT | B7 + SHIFT | | |
| | OUT19 | - | B4 + SHIFT | B4 + SHIFT | B8 + SHIFT | | |
| | OUT20 | - | - | B5 + SHIFT | B9 + SHIFT | | |
| VDD8 | OUT21 | - | - | B6 + SHIFT | B10 + SHIFT | | |
| Cable part: | OUT22 | B7 + SHIFT | B7 + SHIFT | B7 + SHIFT | B11 + SHIFT | | |
| | OUT23 | Activation ou | | | | | |
| VDD1 Cable part: | RCSS 1 | RCSS 1 | | | | | |
| VDD2 Cable part: | RCSS 2 | RCSS 2 | | | | | |
| Cable part: | + 24VDC | + 24 V DC | | | | | |
| Cable part: | 0VDC | 0 V DC | | | | | |



7.1.3 Program Option 2 - Interlocking between the button pair

Note that the interlock does not apply to remaining function (For AQ80 see 9.3.4 and for TX52/55 9.5.4)

| Program Option 2 - Interlocking between the button pair | | | | | | | | |
|---|-----------|---------|----------|------------|----------|--|--|--|
| Supply line | Connector | | F | Cable part | | | | |
| terminal | Connector | 4B | 6B | 8B | 12B/12BD | | | |
| | OUT0 | - | - | - | B1 | | | |
| VDD3 | OUT1 | - | - | - | B2 | | | |
| Cable part: | OUT2 | - | - | - | B3 | | | |
| | OUT3 | - | - | - | B4 | | | |
| | OUT4 | B1 | B1 | B1 | B5 | | | |
| VDD4 | OUT5 | B2 | B2 | B2 | B6 | | | |
| Cable part: | OUT6 | - | B3 | B3 | B7 | | | |
| | OUT7 | - | B4 | B4 | B8 | | | |
| | OUT8 | - | - | B5 | B9 | | | |
| VDD5 | OUT9 | - | - | B6 | B10 | | | |
| Cable part: | OUT10 | B7 | B7 | B7 | B11 | | | |
| | OUT11 | B8 | B8 | B8 | B12 | | | |
| VDD8 | OUT22 | Highsp | eed | | | | | |
| Cable part: | OUT23 | Activat | ion outp | | | | | |
| VDD1 Cable part: | RCSS 1 | RCSS | 1 | | | | | |
| VDD2 Cable part: | RCSS 2 | RCSS | 2 | | | | | |
| Cable part: + 24VDC + 24 V DC | | | | | | | | |
| Cable part: | 0VDC | 0 V DC | ; | | | | | |

| B1 | interlocked with | B2 |
|-----|------------------|-----|
| B3 | interlocked with | B4 |
| B5 | interlocked with | B6 |
| B7 | interlocked with | B8 |
| B9 | interlocked with | B10 |
| B11 | interlocked with | B12 |

| Highspeed |
|--------------------------|
| Step 2 for all buttons |
| activate OUT22 highspeed |



7.1.4 Program Option 3 - Interlocking between the button pair, Shift function

- Note that the interlock does not apply to remaining movements (For AQ80 see 9.3.4 and for TX52/55 9.5.4)
- Note that remaining function never can be shifted in Program 3. (For AQ80 see 9.3.4 and for TX52/55 9.5.4)

| Program Option 3 - Interlocking between the button pair, Shift function | | | | | | | |
|---|-----------|----------------|------------|------------|-------------|------------|--|
| Supply line | Connector | | Fun | ction | | Cable part | |
| terminal | Connector | 4B | 6B | 8B | 12B/12BD | Cable part | |
| | OUT0 | - | - | - | B1 | | |
| VDD3 | OUT1 | - | - | - | B2 | | |
| Cable part: | OUT2 | - | - | - | B3 | | |
| | OUT3 | - | - | - | B4 | | |
| | OUT4 | B1 | B1 | B1 | B5 | | |
| VDD4 | OUT5 | B2 | B2 | B2 | B6 | | |
| Cable part: | OUT6 | - | B3 | B3 | B7 | | |
| | OUT7 | - | B4 | B4 | B8 | | |
| | OUT8 | - | - | B5 | B9 | | |
| Cable north | OUT9 | - | - | B6 | B10 | | |
| Caple part. | OUT10 | B7 | B7 | B7 | B11 | | |
| | | SHIFT (B8) | SHIFT (B8) | SHIFT (B8) | SHIFT (B12) | | |
| | OUT12 | - | - | - | B1 + SHIFT | | |
| VDD6 | OUT13 | - | - | - | B2 + SHIFT | | |
| Cable part: | OUT14 | - | - | - | B3 + SHIFT | | |
| | OUT15 | - | - | - | B4 + SHIFT | | |
| | OUT16 | B1 + SHIFT | B1 + SHIFT | B1 + SHIFT | B5 + SHIFT | | |
| VDD7 | OUT17 | B2 + SHIFT | B2 + SHIFT | B2 + SHIFT | B6 + SHIFT | | |
| Cable part: | OUT18 | - | B3 + SHIFT | B3 + SHIFT | B7 + SHIFT | | |
| | OUT19 | - | B4 + SHIFT | B4 + SHIFT | B8 + SHIFT | | |
| | OUT20 | - | - | B5 + SHIFT | B9 + SHIFT | | |
| VDD8 | OUT21 | - | - | B6 + SHIFT | B10 + SHIFT | | |
| Cable part: | OUT22 | B7 + SHIFT | B7 + SHIFT | B7 + SHIFT | B11 + SHIFT | | |
| | OUT23 | Activation out | put | | | | |
| VDD1 Cable part: | RCSS 1 | RCSS 1 | | | | | |
| VDD2 Cable part: | RCSS 2 | RCSS 2 | | | | | |
| Cable part: | + 24VDC | + 24 V DC | | | | | |
| Cable part: 0VDC 0 V DC | | | | | | | |

| AQ80 | | | TX52/55 | | | |
|------|------------------|----|---------|------------------|-----|--|
| B1 | interlocked with | B2 | B1 | interlocked with | B2 | |
| B3 | interlocked with | B4 | B3 | interlocked with | B4 | |
| B5 | interlocked with | B6 | B5 | interlocked with | B6 | |
| | | | B7 | interlocked with | B8 | |
| | | | B9 | interlocked with | B10 | |



7.1.5 Program Option 4 - Interlocking between the button pair, High speed

- Note that the interlock does not apply to remaining movements (For AQ80 see 9.3.4 and for TX52/55 9.5.4)
- Note that remaining function never can be in highspeed in Program 4. (For AQ80 see 9.3.4 and for TX52/55 9.5.4)

| Program Option 4 - Interlocking between the button pair, Highspeed | | | | | | | |
|--|-------------------------|------------|------------|------------|-------------|------------|--|
| Supply line | Connec- | | Cable next | | | | |
| terminal | tor | 4B | 6B | 8B | 12B/12BD | Cable part | |
| | OUT0 | - | - | - | B1 | | |
| VDD3 | OUT1 | - | - | - | B2 | | |
| Cable part: | OUT2 | - | - | - | B3 | | |
| | OUT3 | - | - | - | B4 | | |
| | OUT4 | B1 | B1 | B1 | B5 | | |
| VDD4 | OUT5 | B2 | B2 | B2 | B6 | | |
| Cable part: | OUT6 | - | B3 | B3 | B7 | | |
| | OUT7 | - | B4 | B4 | B8 | | |
| | OUT8 | - | - | B5 | B9 | | |
| Cable nexts | OUT9 | - | - | B6 | B10 | | |
| Cable part: | OUT10 | B7 | B7 | B7 | B11 | | |
| | | SHIFT (B8) | SHIFT (B8) | SHIFT (B8) | SHIFT (B12) | | |
| | OUT12 | - | - | - | B1 + SHIFT | | |
| VDD6 | OUT13 | - | - | - | B2 + SHIFT | | |
| Cable part: | OUT14 | - | - | - | B3 + SHIFT | | |
| | OUT15 | - | - | - | B4 + SHIFT | | |
| | OUT16 | B1 + SHIFT | B1 + SHIFT | B1 + SHIFT | B5 + SHIFT | | |
| VDD7 | OUT17 | B2 + SHIFT | B2 + SHIFT | B2 + SHIFT | B6 + SHIFT | | |
| Cable part: | OUT18 | - | B3 + SHIFT | B3 + SHIFT | B7 + SHIFT | | |
| | OUT19 | - | B4 + SHIFT | B4 + SHIFT | B8 + SHIFT | | |
| | OUT20 | - | - | B5 + SHIFT | B9 + SHIFT | | |
| VDD8 | OUT21 | - | - | B6 + SHIFT | B10 + SHIFT | | |
| Cable part: | OUT22 | Highspeed | | | | | |
| | OUT23 Activation output | | | | | | |
| VDD1 Cable part: | RCSS 1 | RCSS 1 | | | | | |
| VDD2 Cable part: | RCSS 2 | RCSS 2 | | | | | |
| Cable part: | + 24VDC | + 24 V DC | | | | | |
| Cable part: | 0VDC | 0 V DC | | | | | |





7.1.6 Program Option 5 - Interlocking between the button pair, seperate high speed

| ! | Note that the interlock does not apply to remaining movements |
|---|---|
| • | (For AQ80 see 9.3.4 and for TX52/55 9.5.4) |

| Program Option 5 - Interlocking between the button pair, seperate highspeed | | | | | | | | |
|---|-----------|--|--|--|---|------------|--|--|
| Supply line | Connector | | Fur | iction | | Cable part | | |
| terminal | Connector | 4B | 6B | 8B | 12B/12BD | | | |
| | OUT1 | B1, 1 st & 2 nd | B1, 1 st & 2 nd | B1, 1 st & 2 nd | B5, 1 st & 2 nd | | | |
| | OUT2 | B1, 2 nd | B1, 2 nd | B1, 2 nd | B5, 2 nd | | | |
| Cable part: | OUT3 | B2, 1 st & 2 nd | B2, 1 st & 2 nd | B2, 1 st & 2 nd | B6, 1 st & 2 nd | | | |
| | OUT4 | B2, 2 nd | B2, 2 nd | B2, 2 nd | B6, 2 nd | | | |
| VDD4 | OUT5 | - | B3, 1 st & 2 nd | B3, 1 st & 2 nd | B7, 1 st & 2 nd | | | |
| Cable part: | OUT6 | - | B3, 2 nd | B3, 2 nd | B7, 2 nd | | | |
| | OUT7 | - | B4, 1 st & 2 nd | B4, 1 st & 2 nd | B8, 1 st & 2 nd | | | |
| | OUT8 | - | B4, 2 nd | B4, 2 nd | B8, 2 nd | | | |
| VDD5 | OUT9 | - | - | B5, 1 st & 2 nd | B9, 1 st & 2 nd | | | |
| Cable part: | OUT10 | - | - | B5, 2 nd | B9, 2 nd | | | |
| | OUT11 | - | - | B6, 1 st & 2 nd | B10, 1 st & 2 nd | | | |
| | OUT12 | - | - | B6, 2 nd | B10, 2 nd | | | |
| VDD6 | OUT13 | B7, 1 st & 2 nd | B7, 1 st & 2 nd | B7, 1 st & 2 nd | B11, 1 st & 2 nd | | | |
| Cable part: | OUT14 | B7, 2 nd /REM | B7, 2 nd /REM | B7, 2 nd /REM | B11, 2 nd /REM | | | |
| | OUT15 | B1-B2, 1 st & 2 nd | B1-B4, 1 st & 2 nd | B1-B6, 1 st & 2 nd | B5-B10, 1 st & 2 nd | | | |
| VDD7 Cable part: | OUT16 | B8, 1 st /REM | B8, 1 st /REM | B8, 1 st /REM | B12, 1 st /REM | | | |
| VDD1 Cable part: | RCSS 1 | RCSS 1 | | | | | | |
| VDD2 Cable part: | RCSS 2 | RCSS 2 | | | | | | |
| Cable part: | + 24VDC | + 24VDC | | | | | | |
| Cable part: | 0VDC | 0VDC | | | | | | |

1st = Button first step 2nd = Button second step REM = Button remaining

B8 remaining disable 2nd step for B1-B6 (Micro), on Era 8B with display

| AQ80 | | | | | | | |
|------|------------------|----|--|--|--|--|--|
| B1 | interlocked with | B2 | | | | | |
| B3 | interlocked with | B4 | | | | | |
| B5 | interlocked with | B6 | | | | | |

| TX52/55 | | | | | | |
|---------|---------------------|-----|--|--|--|--|
| B5 | interlocked with | B6 | | | | |
| B7 | B7 interlocked with | | | | | |
| B9 | interlocked with | B10 | | | | |

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8 Derating

The maximum possible total output current of the T-Rx 500 receiver is more than 30 A. As the internal switch losses in the receiver generates heat the maximum output current can not be used over the whole specified temperature range.

8.1 Convection cooling

If a T-Rx 500 receiver is located in free, quasi-stationary air (convection cooling) the maximum allowed output current must be reduced according to Figure 10.



Figure 10. Convection cooling. Maximum allowed output current versus ambient temperature



9 Commissioning

9.1 Frequency setting

The radio transmission used in the T-Rx Std. systems can use either a frequency hopping transmission scheme or scan mode were frequency are automatically selected. The default factory setting is frequency hopping which is recommended for most applications.

Note! The transmitter and receiver must have the same frequency setting.

Frequency hopping

Frequency band 400 uses frequency hopping transmission. When frequency hopping is selected, the frequency changes automatically between 15 different frequencies in the frequency-band.

Scan mode

Scan free frequency

Scan free frequency scheme automatically scans between 15 different frequencies and one frequency in the frequency-band will be used. The transmitter changes to a free frequency every time it's started, as long as the transmitter searches for a free frequency the status indicator glows yellow.

Fixed frequency

Fixed frequency channel set by the user. For Receiver see section 9.1.1, and for transmitter, see section 9.3.3 for AQ80 and section 9.5.3 for TX52/55.

9.1.1 Radio frequency setting in Receiver RXO

This setting is made in the RXO manager. Refer to 951538-000 Manager manual RXO.



9.2 Overview transmitters

9.2.1 Place symbol label

Alongside the buttons there is room for a symbol label. A sheet of symbol labels are included with the delivery.

- 1. Before placing the label, clean the surface with alcohol (do not use isopropyl alcohol).
- 2. Place the label; make sure that the symbol label is placed at the right button!





9,3 AQ80 with Display Transmitter configuration mode

Enter configuration menu

Press button B8 (2nd step) while pulling up the safety stop button. Hold down the button 3 seconds until the status indicator glows yellow showing that the transmitter is in configuration mode.

Submenu

Browse submenu with the buttons B1 and B2. Choose submenu with button B8. To return to the main menu while you are in a submenu, press button B7.

Submenus:

- "Shutdown" •
- "PIN-code" •
- "Frequency"
 - "433 MHz"
- "Button function"
- "Radio comm power"
- "FX sequence"
- "System info"

Exit/Save

Finish by turning the transmitter off by pushing the safety stop button down. This also saves the changes that have been made.

9.3.1 Shutdown Time of the Transmitter

The transmitter shuts down automatically if not used for a certain amount of time. This time can be adjusted in the transmitter configuration menu.

- 1. Enter the configuration menu.
- 2. Then select "Shutdown" with B8 (browse with B1 and B2).
- 3. Then browse the desired shutdown time with B1 and B2:
 - "2 minutes" •
 - "5 minutes"
 - "15 minutes"
 - "no shutdown" •

Already selected shutdown time is indicated by button LED B1.

- 4. Select shutdown time by press down button B8.
- 5. Automatic return to the main menu or restart the transmitter.







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9.3.2 PIN-code Configuration of the Transmitter

The transmitter is equipped with a user configurable PIN-lock to prevent unauthorized access to the system. The PIN-lock is disabled by default.

- 1. Enter the configuration menu.
- 2. Then select "PIN-code" with B8 (browse with B1 and B2).
- Enter PIN: For enable enter the factory setting 3333 and for disable enter the old PIN-code.
 Press B1 repeatedly to select number and B8 to choose the number. Delete a number with B2.
- 4. Enter new PIN: Enter the new 4-digit PIN. For enable enter the new PIN (not 3333) and for disable enter the factory setting 3333.
- 5. Repeat PIN: Repeat the PIN code.
- 6. Automatic return to the main menu or restart the transmitter.



9.3.2.1 Entering PIN-code at start-up

When PIN is enabled the transmitter will not start to transmit before the correct PIN-code is entered. If the transmitter is PIN locked at startup status indicator shows red continuous light. Display will show "Enter PIN".

Enter the 4-digit PIN-code by press B1 repeatedly to select number and B8 to choose the number. Delete a number with B2. When all 4-digit are selected, press B8 once again to select the PIN code.

At successful login the status indicator shows green flashing. Display shows "PIN OK!". The unit is now in operating mode.

9.3.3 Radio Frequency Setting in the AQ80 Transmitter

To change the settings do the following:

- 1. Enter the configuration menu.
- 2. Then select "Frequency" with B8 (browse with B1 and B2).
- 3. Then browse to the desired setting with B1 and B2.
 - "Frequency hopping"
 - "Scan mode"
 - "Channel 0-XX"

Already selected setting is shown when entering the frequency setting menu.

- 4. Select setting by press down button B8.
- 5. Automatic return to the main menu or restart the transmitter.
- **Frequency hopping:** When frequency hopping is selected, the frequency changes automatically between different frequencies in the frequency-band.
- Scan Mode: Automatically scans between different frequencies and one frequency in the frequencyband will be used. The transmitter changes to a free frequency every time it's started, the scan will start at the same frequency that was used last time the transmitter was started.
- **Channel:** Sets a specific channel. See "9.3.3.2 Fixed frequency" on page 27.



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In frequency band 400 there is an opportunity to select region.

- 1. Enter the configuration menu.
- 2. Then select "433 MHz" with B8 (browse with B1 and B2).
- 3. Then browse to the desired setting with B1 and B2.
 - "EU"
 - "Other"

Already selected setting is indicated by button LED B1.

- 4. Select setting by press down button B8.
- 5. Automatic return to the main menu or restart the transmitter.
- Note. If the equipment is being operated in EU-region this setting has to be set to EU for correct fulfill the regulation! See "Appendix 1 European Radio Regulation" on page 39.
- For Other make sure to fulfill any rules or regulations or any applicable local, state, or federal governing laws.





9.3.3.2 Fixed frequency

| Channel no | 434MHz EU | 433-434MHz Other |
|------------|-----------|------------------|
| 0 | 434,05 | 433,3 |
| 1 | 434.075 | 433,325 |
| 2 | 434.1 | 433.35 |
| 3 | 434,125 | 433,375 |
| 4 | 434 15 | 433.4 |
| 5 | 13/ 175 | 133 125 |
| 6 | 131 2 | 133.45 |
| 7 | 434 225 | 422 475 |
| 0 | 434,223 | 433,475 |
| 0 | 434,23 | 433,5 |
| 9 | 434,273 | 433,323 |
| 10 | 434,3 | 433,33 |
| 10 | 434,325 | 433,575 |
| 12 | 434,35 | 433,6 |
| 13 | 434,375 | 433,625 |
| 14 | 434,4 | 433,65 |
| 15 | 434,425 | 433,675 |
| 16 | 434,45 | 433,7 |
| 17 | 434,475 | 433,725 |
| 18 | 434,5 | 433,75 |
| 19 | 434,525 | 433,775 |
| 20 | 434,55 | 433.8 |
| 21 | 434.575 | 433.825 |
| 22 | 434.6 | 433.85 |
| 23 | 434 625 | 433.875 |
| 24 | 434 65 | 433.0 |
| 25 | 434 675 | 433.025 |
| 25 | 434,073 | 433,923 |
| 20 | 434,7 | 433,95 |
| 27 | 434,725 | 433,975 |
| 28 | 434,75 | 434 |
| 29 | 434,775 | 434,025 |
| 30 | | 434,05 |
| 31 | | 434,075 |
| 32 | | 434,1 |
| 33 | | 434,125 |
| 34 | | 434,15 |
| 35 | | 434,175 |
| 36 | | 434,2 |
| 37 | | 434,225 |
| 38 | | 434,25 |
| 39 | | 434,275 |
| 40 | | 434,3 |
| 41 | | 434.325 |
| 42 | | 434.35 |
| 43 | | 434 375 |
| 11 | | 434.4 |
| 15 | | 434 425 |
| 40 | | 134,423 |
| 40 | | 404,40 |
| 4/ | | 404,470 |
| 48 | | 434,5 |
| 49 | | 434,525 |
| 50 | | 434,55 |
| 51 | | 434,575 |
| 52 | | 434,6 |
| 53 | | 434,625 |
| 54 | | 434,65 |
| 55 | | 434,675 |
| 56 | | 434,7 |
| 57 | | 434,725 |
| 58 | | 434.75 |
| 50 | | 121 775 |
| 59 | | 434,775 |

Table 2.Fixed frequency list

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9.3.4 Adjustment of the Push Buttons Remaining and Momentary Functions

The buttons either have momentary functions, which give a signal for only as long as you keep pressing, or remaining functions.



Note that this function needs support from the receiver PLC. Before changing these parameters, check the program options. Only qualified personnel may make these changes.

- 1. Enter the configuration menu.
- 2. Then select "Button function" with B8 (browse with B1 and B2).
- 3. Press down the buttons for which you want to have a remaining/momentary function. Lighted button LED indicates remaining function. Note: The three pair of buttons 1-2, 3-4 and 5-6 must have the same settings within the pair. Otherwise the momentary function is disabled on the button that is not remaining.
- 4. Restart the transmitter.

9.3.5 Radio communication power

To change the settings do the following:

- 1. Enter the configuration menu.
- 2. Then select "Radio comm power" with B8 (browse with B1 and B2).
- 3. Then browse to the desired setting with B1 and B2.
 - "Auto power"
 - "100 % power"
 - "25 % power"

Already selected setting is indicated by button LED B1.

- 4. Select setting by press down button B8.
- 5. Automatic return to the main menu or restart the transmitter.

9.3.6 FX sequence

To change the settings do the following:

- 1. Enter the configuration menu.
- 2. Then select "FX sequence" with B8 (browse with B1 and B2).
- 3. Then browse to the desired setting with B1 and B2.
 - "255 X:XX Disabled"
 - "000 0:0 119 7:14"

Already selected setting is the first one that comes up when entering the menu.

- 4. Select setting by press down button B8.
- 5. Automatic return to the main menu or restart the transmitter.

9.3.7 System info

Shows firmware version for the CIM card, ID number and package rate. Press any of the two bottom buttons for exit this menu.







9.4 AQ80 without display Transmitter configuration mode

Enter configuration menu

Press button B8 (2nd step) while pulling up the safety stop button. Hold down the button 3 seconds until the status indicator glows blue, showing that the configuration mode is available. Release the button. Blue light goes out and submenus can be chosen.

Submenu

There are three submenus. Choose desired submenu with buttons:

- B1: "Shutdown"
- B2: "Frequency"
- B7: "Radio comm power"



Enter config menu

9.4.1 Submenu B1: "Shutdown" - Shutdown Time of the Transmitter

The transmitter shuts down automatically if not used for a certain amount of time. This time can be adjusted in the transmitter configuration menu.

- 1. Enter the configuration menu.
- 2. Then select "Shutdown" with B1.
- 3. Then choose the desired shutdown time:

| Button | Shutdown time | Indication (looped) |
|--------|---------------|---------------------|
| B1 | 2 minutes | • |
| B2 | 5 minutes | \mathbf{O} |
| B7 | 15 minutes | |
| B8 | no shutdown | |

Already selected shutdown time see indication.

4. Restart the transmitter.





9.4.2 Submenu B2: "Frequency" - Radio Frequency Setting in the Transmitter

To change the settings do the following:

- 1. Enter the configuration menu.
- 2. Then select "Frequency" with B2.
- 3. Then choose the desired frequency setting:

| Button | Setting | Indication (looped) |
|--------|-------------------|------------------------------|
| B1 | Frequency hopping | $\bigcirc \bigcirc \bigcirc$ |
| B2 | Scan free | |

Already selected setting see indication.

- 4. Restart the transmitter.
- **Frequency hopping:** When frequency hopping is selected, the frequency changes automatically between different frequencies in the frequency-band.
- Scan free: Automatically scans between different frequencies and one frequency in the frequency-band will be used. The transmitter changes to a free frequency every time it's started, the scan will start at the same frequency that was used last time the transmitter was started.

9.4.3 Submenu B7: "Radio comm power" - Radio communication power

To change the settings do the following:

- 1. Enter the configuration menu.
- 2. Then select "Radio comm power" with B7.
- 3. Then choose the desired setting:

| Bu | tton | Setting | Indication (looped) |
|----|------|------------|---|
| B1 | | Auto power | |
| B2 | | 100% power | $\bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc$ |
| B7 | | 25% power | |

Already selected setting see indication.

4. Restart the transmitter.







9.5 TX52/55 Transmitter configuration

9.5.1 Shutdown time

The transmitter shuts down automatically if not used for a certain amount of time. This time can be adjusted using the buttons on the transmitters.

- 1. Press button 11 (step 2) and button 7 while releasing the safety stop button. Hold the buttons for 3 seconds until the status indicator glows yellow (shall change from green to yellow) showing that the transmitter is in setup-mode. The display shows "Auto-Off Config" showing that the transmitter is in setup-mode.
- 2. Then select shutdown time by pressing button for the selected mode.
 - Button $5 = 2 \min$
 - Button $6 = 5 \min$
 - Button $7 = 15 \min$
 - Button 8 = no shutdown
- 3. A green LED indicates which button has been selected.
- 4. Restart the transmitter.

9.5.2 PIN Configuration

The transmitter is equipped with a user configurable PIN-lock to prevent unauthorized access to the system. The PIN-lock is disabled by default.

9.5.2.1 Enable PIN

- 1. Press button B11 (step 2) and button B8 while releasing the safety stop button. Hold the buttons for 3 seconds until the status indicator indicates configuration mode. When entering this mode LED L1 and L2 will be lit. The display shows "Enter PIN".
- 2. Enter the factory setting 3333 with the buttons B1-B8.
- 3. If PIN ok LED L1, L2 and L3 will be lit. Display shows "PIN OK!" "Enter new PIN". Enter the new 4-digit PIN with the buttons B1-B8. Do not use the code 3333.
- 4. During this step LED L1, L2, L3 and L4 will be lit. Display shows "Repeat new PIN" Repeat new 4-digit PIN. Display shows "PIN set OK!" if successful.
- 5. If PIN set OK L5 will be lit. Display shows "Restart unit". Restart the transmitter to activate the new setting.

9.5.2.2 Disable PIN

Repeat the above procedure (section "9.5.2.1 Enable PIN"). Enter the old PIN and 3333 as the new PIN (factory setting). Restart the transmitter to activate the new setting.

9.5.2.3 Entering PIN at start-up

| | When PIN is enabled the transmitter will not start to transmit before the correct | B1= | 1 |
|------------------------|---|-----|---|
| | PIN code is entered. | B2= | 2 |
| | Indications when PIN-locked: L1 and L2 will be lit and the status indicator will | B3= | 3 |
| be steady RED. Display | be steady RED. Display will show Enter Filv. | B4= | 4 |
| | Enter the 4-digit PIN with the buttons B1-B8. | B5= | 5 |
| Display shows | Display snows "PIN OK!" at successful login. | B6= | 6 |
| | | B7= | 7 |
| | | B8= | 8 |

9.5.3 Radio Frequency Setting in the TX52/55 Transmitter

To change the settings do the following:

- 1. Press button 10 (step 2) and button 11 while pulling up the safety stop button. Hold down the buttons in 3 seconds until the status indicator glows yellow (shall change from green to yellow) showing that the transmitter is in setup-mode. The display also show information during this setting.
- 2. Set all buttons to OFF (○) for frequency hopping or to ON (●) for scan mode, button ON is indicated by the button LED glowing green. See Table 3 for fixed frequency setting.
- Note all other combinations except in this table are reserved
- 3. Finish by turning the transmitter off by pushing the safety stop button down.

| Channel no | B1 | B2 | B3 | B4 | B5 | B6 | B7 | B8 | |
|------------|----|----|----|----|----|----|---------|----|-------------------|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Frequency hopping |
| 1 | | 0 | 0 | 0 | 0 | 0 | \circ | 0 | Fixed channel |
| 2 | 0 | | 0 | 0 | 0 | 0 | 0 | 0 | |
| 3 | | | 0 | 0 | 0 | 0 | 0 | 0 | |
| 4 | 0 | 0 | | 0 | 0 | 0 | 0 | 0 | |
| 5 | | 0 | | 0 | 0 | 0 | 0 | 0 | |
| 6 | 0 | | | 0 | 0 | 0 | 0 | 0 | |
| 7 | | | | 0 | 0 | 0 | 0 | 0 | |
| 8 | 0 | 0 | 0 | | 0 | 0 | 0 | 0 | |
| 9 | | 0 | 0 | | 0 | 0 | 0 | 0 | |
| 10 | 0 | | 0 | | 0 | 0 | 0 | 0 | |
| 11 | | | 0 | | 0 | 0 | 0 | 0 | |
| 12 | 0 | 0 | | | 0 | 0 | 0 | 0 | |
| 13 | | 0 | | | 0 | 0 | 0 | 0 | |
| 14 | 0 | | | | 0 | 0 | 0 | 0 | |
| 15 | | | | | 0 | 0 | 0 | 0 | |
| 16 | 0 | 0 | 0 | 0 | | 0 | 0 | 0 | |
| 17 | | 0 | 0 | 0 | | 0 | 0 | 0 | |
| 18 | 0 | | 0 | 0 | | 0 | 0 | 0 | |
| 19 | | | 0 | 0 | | 0 | 0 | 0 | |
| 20 | 0 | 0 | | 0 | | 0 | 0 | 0 | |
| 21 | | 0 | | 0 | | 0 | 0 | 0 | |
| 22 | 0 | | | 0 | | 0 | 0 | 0 | |
| 23 | | | | 0 | | 0 | 0 | 0 | |
| 24 | 0 | 0 | 0 | | | 0 | 0 | 0 | |
| 25 | | 0 | 0 | ٠ | | 0 | 0 | 0 | |
| 26 | 0 | | 0 | | | 0 | 0 | 0 | |
| 27 | | | 0 | | | 0 | 0 | 0 | |
| 28 | 0 | 0 | | | | 0 | 0 | 0 | |
| 29 | | 0 | | | | 0 | 0 | 0 | |
| 255 | | | | | | | | | Scan mode |

Table 3. Frequency setting list for TX52/55



9.5.4 Adjustment of the push button functions

The buttons either have momentary functions, which give a signal for only as long as you keep pressing, or a remaining function. The button LED indicates an active remaining function.

- 1. Press button 11 (step 2) and button 9 while releasing the safety stop button. Hold down the buttons in 3 sec. until the status indicator glows yellow (shall change from green to yellow) showing that the transmitter is in setup-mode. The display shows "Button Config" showing that the transmitter is in setup-mode.
- 2. Then press down the buttons for which you want to have a remaining function and the LEDs next to the buttons will light up.
- 3. Restart the transmitter.



9.6 Pairing of transmitter and receiver

Status indicator LED 5 and the pairing push button (see Figure 5) on the MAIN board should be used when pairing the receiver and transmitter.

- 1. Open the service hatch on the receiver. Press the pairing button in the receiver.
- Set the transmitter in pairing mode.
 AQ80: Hold down button B7 and B8 when starting the transmitter. Continue to press the buttons for ≈5 seconds.
 TX52/55: Hold down button B11 and B12 when starting the transmitter.

Continue to press the buttons for \approx 5 seconds.

- 3. See pairing indications, next section. When paired LED 5 shows steady green. If this hasn't been indicated within 15 seconds restart the transmitter.
- 4. Restart the system to activate the new ID number.

The receiver has now learned the transmitter ID number and will only accept commands from that transmitter.





9.6.1 Pairing indications

| Mode | Event | Status indicator receiver | Flash rate |
|---------|-----------------|---------------------------|------------|
| Pairing | In pairing mode | Green/yellow | 50/50 ms |
| | Paired | Steady green | |

 Table 4.
 Receiver pairing indication

| Mode | Event | Status indicator transmitter | Flash rate |
|-----------------|------------|------------------------------|------------|
| In pairing mode | Not paired | Green/yellow | 50/50 ms |
| | Paired | Steady green | |

Table 5. Transmitter pairing indication

| Pairing: | Pairing ready: | Link timeout: |
|----------------------|----------------------|-----------------------|
| Pair mode Pairing | Pair mode Paired! | Pair mode Failed! |
| | ↓ | \downarrow |
| | Restart System! | Restart Pair mode! |

 Table 6.
 Transmitter display pairing indication

9.7 CIM Card

The CIM card is used for storing configuration information. You can take out the CIM-module from one system and place it in a spare transmitter with the same system program and it will work exactly* the same.



This exchange has to be done in a clean, dry and ESD safe environment.

- To avoid personal and/or damages on property; exchange CIM card ONLY when the transmitter battery has been removed.
- *Note that some settings do not follow with the AQ80 CIM card and need to be set in the "spare" transmitter. These settings are; Radio comm power, FX sequence 0-119.

9.7.1 Removing/Mounting CIM Card AQ80



 To disassemble the transmitter, remove the battery, unscrew the six screws* holding the back cover of the transmitter, pull up the back of the transmitter carefully and pull out the connector for the battery and remove the back enclosure entirely.
 *Note that the screw below the battery is underneath the type label. Make a

"Note that the screw below the battery is underneath the type label. Make a little cut on the type label around the screw; so not the entire type label is damage when removing the screw.

- 2. The CIM card (1) is located at the top of the transmitter (above the display board ⁽²⁾, for transmitter with display). Gently remove the CIM card straight up.
- 3. Install the CIM card primarily in the original transmitter, alternative spare transmitter. Be sure to insert the CIM card properly in its connector.
- 4. Reinstall the enclosure. The screws should be tightened with 0.35Nm±0.05.
- 5. Insert battery. Now, the transmitter is ready for operation.

9.7.2 Removing/Mounting CIM Card TX52/55



- 1. Remove the battery. Unscrew the CIM card cover (1), 4 screws.
- 2. Gently remove the CIM card ⁽³⁾ straight up.
- 3. Pull out the 3-pole CIM card power supply (2).
- 4. Install primarily original CIM card, alternative exchange CIM card. Be sure to insert the CIM card in its connector, the upper row of holes, see labeling Key-Id 4.
- 5. Mount the power supply connector (note that the connection cables must be placed beside the CIM card).
- 6. Reinstall CIM card cover. The screws should be tightened with 1 Nm.

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7. Insert battery. Now, the transmitter is ready for operation.

10 Function tests

Before the following test is performed, make sure to prevent unintended movements of the controlled object from becoming a safety hazard.

Check that the transmitter can control the receiver by testing all functions and note if the output relays and the corresponding inputs on the controlled object are activated.

Follow the local safety regulations for the equipment and start the equipment as described in the Operator Manual.

Check the following:

- Are all movements correct?
- Do the other functions operate correctly?
- Does the stop function on the transmitter work properly?
- Also test the stop function by removing the battery in the transmitter.
- Is it possible to control the equipment from the normal controllers? If it is possible to operate the equipment from more than one controller at a time the system is incorrectly installed.
- There should be a changeover switch between radio/pendant controls to prevent control from two places at the same time.
- Test that all the safety and stop limits switches work.

This list of test is for reference only and can be extended by the system integrator in the specific installations and the corresponding risk analysis.

11 Indications

11.1 Receiver indications

Status indicator, see "Figure 4. Receiver back side".

| Mode | Event | Status LED | Flash rate |
|-----------|----------------------------|--------------|------------|
| Status OK | Not connected | Fast GREEN | 50/50 ms |
| | CONNECTED, RCSS=ON | Slow GREEN | 30/970 ms |
| | CONNECTED, RCSS=OFF | Medium GREEN | 50/250 ms |
| ERROR | Receiver internal error | Steady RED | |
| | Transmitter internal error | Fast RED | 50/50 ms |
| | No supply power | Off | |

Table 7. Indications on the Receiver back side



11.2 Transmitter indications

11.2.1 Status indicator

If the transmitter under start up (if not PIN locked) or operation detects a fault in any of the transmitters self-tests, the status indicator (see section 9.2) will indicate a continuous red light, after which the transmitter is shut down.

| INDICATIONS | EXPLANATIONS |
|---|---|
| Green flashing | OK, normal operation |
| Yellow quick flashing | Battery voltage low <3.5 V |
| Yellow continuous, during operating | Battery empty. Transmitter will shut-off within 10s |
| Yellow continuous, at start-up | Configuration mode |
| Red continuous, at start-up | PIN locked |
| Red continuous, during operation | Hardware fault |
| Blue continuous, other indications may occur simultaneously | High power (only AQ80) |

 Table 8.
 Indications of the transmitter's status indicator

11.2.2 Display indications

These default symbols can appear on the display depending on the configuration. For configuration refer to Display control mapping RXO Std.



- 1. Radio signal / MC
- Text field (optional)
 Battery level

11.2.2.1 Radio signal quality

| No radio link established | Weak signal | Good signal | Strong signal | Very strong signal |
|---------------------------|-------------|-------------|---------------|--------------------|
| \times | - | - | | |

MC on is indicated by a line beneath the radio signal symbol, example **....**

11.2.2.2 Text field (option)

This text is configured in the receiver (8 characters) using the RXO manager.

11.2.2.3 Battery level

| Battery empty | 25% | 50% | 75% | 100% (fully charged) |
|---------------|-----|-----|-----|----------------------|
| D | Þ | Þ | ∎D | • • |



12 Trouble shooting

On push button transmitter:

Ensure that a charged battery is inserted in the transmitter.

The status indicator indicates following:

- Slow green flashing means that the transmitter is fully operational
- · Fast yellow flashing means that the battery needs charging
- · Steady yellow light means that the transmitter is in configuration mode
- Steady red light at start up means that the transmitter is PIN locked
- Steady red light during operating means that an error in the transmitter has been discovered and it will shut itself down

In receiver:

• Check the indications of mode "ERROR, see Table 7 on page 36

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Appendix 1 - European Radio Regulation

Exerpts from ERC RECOMMENDATION 70-03:

| Frequency Band Power / Magnetic Fiel | | Power / Magnetic Field | Spectrum ac- cess and mitiga- tion requirement | Channel spacing | Notes |
|---|------------------------------------|--|--|--|--|
| f | 433.050-434.790 MHz (note 4) | 10 mW e.r.p. | < 10 % duty cycle (note 1) | No spacing | |
| f1 | 433.050-434.790 MHz (note 4bis) | 1 mW e.r.p. -13 dBm/10 kHz | No requirement | No spacing | Power density limited to -13 dBm/10 kHz for wideband modu- lation with a bandwidth greater than 250 kHz |
| f2 | 434.040-434.790 MHz (note 4bis) | 10 mW e.r.p. | No requirement | Up to 25 kHz | |
| g | 863-870 MHz (note 3, 4 and 6) | ≤ 25 mW e.r.p. | ≤ 0.1% duty cycle or LBT (note 1 and 5) | ≤ 100 kHz for 47 or more channels (note 2) | FHSS modulation |
| | | ≤ 25 mW e.r.p. (note 6) Power density : - 4.5 dBm/100 kHz (note 7) | ≤ 0.1% duty cycle or LBT+AFA (note 1, 5 and 6) | No spacing | DSSS and other wideband modulation other than FHSS |
| | | ≤ 25 mW e.r.p. | ≤ 0.1% duty cycle or LBT+AFA (note 1 and 5) | ≤ 100 kHz, for 1 or more channels modulation bandwith ≤ 300 kHz (note 2) | Narrow /wide-band modulation |
| g1 | 868.000-868.600 MHz (note 4) | ≤ 25 mW e.r.p. | ≤ 1% duty cycle or LBT+AFA (note 1) | No spacing, for 1 or more channels (note 2) | Narrow / wide-band modulation. No channel spacing, however the whole stated frequency band may be used |
| g2 | 868.700-869.200 MHz (note 4) | ≤ 25 mW e.r.p. | ≤ 0.1% duty cycle or LBT+AFA (note 1) | No spacing, for 1 or more channels (note 2) | Narrow / wide-band modulation. No channel spacing, however the whole stated frequency band may be used |
| g3 | 869.400-869.650 MHz | ≤ 500 mW e.r.p. | ≤ 10% duty cycle or LBT+AFA (note 1) | 25 kHz (for 1 or more channels) | Narrow / wide-band modulation The whole stated frequency band may be used as 1 channel for high speed data transmission |
| g4 | 869.700-870.000 MHz | ≤ 5 mW e.r.p. | No requirement | No spacing | Narrow / wide-band modulation. |
| | | ≤ 25 mW e.r.p. | up to 1% duty cycle or LBT+AFA (note 1) | (IOF I OF MORE CHARNES) | the whole stated frequency band may be used |

Note 1: When either a duty cycle, Listen Before Talk (LBT) or equivalent technique applies then it shall not be user dependent/adjustable and shall be guaranteed by appropriate technical means. For LBT devices without Adaptive Frequency Agility (AFA), or equivalent techniques, the duty cycle limit applies. For any type of frequency agile device the duty cycle limit applies to the total transmission unless LBT or equivalent technique is used.

Note 2: The preferred channel spacing is 100 kHz allowing for a subdivision into 50 kHz or 25 kHz.

Note 4: Note 4: Audio and video applications are allowed provided that a digital modulation method is used with a max. bandwidth of 300 kHz. Analogue and digital voice applications are allowed with a max. bandwidth ≤ 25 kHz.

In sub-band 863-865 MHz voice and audio conditions of Annexes 10 and 13 of ERC/REC 70 – 03 apply respectively.

Note 4bis: Audio and video applications are excluded. Analogue or digital voice applications are allowed with a max. bandwidth ≤ 25 kHz and with spectrum access technique such as LBT or equivalent. The transmitter shall include a power output sensor controlling the transmitter to a maximum transmit period of 1 minute for each transmission

Note 5: Duty cycle may be increased to 1% if the band is limited to 865-868 MHz.

Note 6: For other wide-band modulation than FHSS and DSSS with a bandwidth of 200 kHz to 3 MHz, duty cycle can be increased to 1% if the band is limited to 865-868 MHz and power to ≤10 mW e.r.p.





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